

TT: SORTING PARTIALLY ORDERED SETS

Setup

Our goal will be to talk about high dimensional convex geometry through an application towards sorting partially ordered sets

First some definitions...

1. A partially ordered set is a pair (X, \leq) where X is a set and \leq is a binary relation such that

- \leq is reflexive: $x \leq x \quad \forall x \in X$

- \leq is transitive: if $x \leq y$ and $y \leq z$ ~~\implies~~ then $x \leq z$

- \leq possesses weak anti-symmetry: if $x \leq y$ and $y \leq x$ then $x=y$.

Now note that \leq may be a partial ordering meaning $x \leq y$ may not be defined $\forall x, y \in X$. Hence...

2. An ordering is linear if $\forall x, y \in X$ we have

$$x \leq y \quad \text{or} \quad y \leq x.$$

3. From an ordering \leq we can extend it in a consistent way. Call ~~another~~ ~~order~~ a linear ordering

\leq a linear extension of \leq if

pairs identified under \leq \subseteq pairs identified under \leq

that is to say the ordering \leq $\xrightarrow{\text{implies}}$ \leq .

- There could be many linear extensions of a \leq .

i.e. suppose for $X = \{~~a, b, c~~\} \{a, b, c\}$

we only know $a \leq b$ ~~and $b \leq c$~~

◦ \leq defined via $a \leq b$ and $b \leq c$ is consistent

◦ \leq defined via $c \leq a$ and $a \leq b$ is fine.

- let $E(\leq) := \{ \leq : \leq \text{ is a linear extension of } \leq \}$

- Let $e(\leq) := |E(\leq)|$

Now the ~~problem~~: model:

We are given a set X w/ a ordering \leq and our goal
linear

IS to sort X according to \leq

- We can get information by making binary comparisons of the form

1. Choose $a, b \in X$

2. Ask oracle if $a \leq b$ or $b \leq a$.

Our algorithm can be adaptive meaning it can change its heuristic according to previously asked queries to the oracle.

- To be more precise, the algorithm can change the order of pairs $a, b \in X$ sent to the oracle based on previous responses.

- In comparison, a non-adaptive strategy must fix the order of items it provides to the oracle.

~~For reqs~~

The problem :

In usual sorting we start w/ no information

A well known lower bound on the # of comparisons

required is $\Theta(\Omega(n \log n))$ where $n = |X|$.

In ~~today's setting~~, we are given ~~partial information~~

Claim: Any binary comparison sort requires $\Omega(n \log n)$ comparisons.

Proof: Consider ~~that~~ ~~a~~ query ~~at~~ all possible ways to sort n items. A query of the form

$$a \leq b \quad \text{or} \quad b \leq a$$

will allow you to throw away ^{at most} half of the possible permutations.

— if $a \leq b$, throw away all those where $b \leq a$
this means ~~at least~~ ^{at least} $\log(\# \text{ permutations})$ comparisons are required to recover the sorted list.

$$\# \text{ permutations} = n! \quad \rightarrow \quad \log(n!) = \Omega(n \log n) \quad \square$$

What if we were given partial information? ~~is~~

The problem is as follows...

Input: (X, \leq, \preceq) :

- X set of elements
- \leq linear order on X
- \preceq partial order such that \leq is a linear extension of \preceq .

Output: ~~How many~~ sorted X

- Critically we ask how many comparisons are required to sort X .

Building Intuition

Okay ~~how do we normally sort?~~ What does sorting mean here?

- w/ no information, it's like you're choosing one linear extension of the \emptyset binary relation
 - the lower bound is $\log(\# \text{ permutations})$ comparisons
 - indeed $e(\emptyset) = \# \text{ permutations} = n!$
- w/ information such as \preceq , ~~can we hope to sort w/~~

~~at most $\log(e(\leq))$ comparisons?~~

~~Answer is yes.~~

we can run the same argument and derive a lower bound on # of comparisons to be..

$$\log(e(\leq))$$

But is this lower-bound tight? Can we always sort in at most $\log(e(\leq))$ comparisons?

Efficient Comparison Theorem

Yeah...

Theorem (Efficient Comparison): Let (X, \leq) be a poset and suppose \leq is NOT linear. $\exists a, b \in X$ s.t.

$$f \leq \frac{e(\leq + (a, b))}{e(\leq)} \leq 1 - \delta$$

where $f > 0$ is an absolute constant, $\leq + (a, b)$ denotes the transitive closure of $\leq \cup \{(a, b)\}$.
i.e. we know $a \leq b$.

This means that we always make progress toward the right ordering if we choose a, b as in the theorem.

- Concretely what we can do is the following.

[i. At every step i choose (a_i, b_i) as in the algorithm.]

Let $\xi_{i+1} = \xi_i + (a_i, b_i)$. Theorem then says...

$$e(\xi_{i+1}) \leq \frac{e(\xi_{i+1})}{e(\xi_i)} \leq 1 - \delta.$$

$$\rightarrow e(\xi_{i+1}) \leq (1 - \delta) e(\xi_i)$$

every iteration decreases # of linear completions by $(1 - \delta)$ multiplicative factor...

- how large can i be until $e(\xi_{i+1}) = 1$?

$$\begin{aligned} e(\xi_{i+1}) &\leq (1 - \delta) e(\xi_i) \\ &\leq (1 - \delta)^2 e(\xi_{i-1}) \\ &\dots \\ &\leq (1 - \delta)^i e(\xi_1) \end{aligned}$$

For what value of i is $e(\xi_{i+1}) \geq 1$?

$$1 \leq (1-\delta)^i \cdot e(\leq)$$

$$\frac{1}{(1-\delta)^i} \leq e(\leq)$$

~~$$i \leq \log \left(\frac{1}{1-\delta} \right) \log e(\leq)$$~~

$$i \leq \log_{1-\delta} (e(\leq))$$

If $i = \lceil \log_{1-\delta} (e(\leq)) \rceil$ then done.

- What is δ ?

- Some conjecture that $\delta = \frac{1}{3}$. Since it is tight w/ the poset



- We'll use $\delta = \frac{1}{2e} \approx 0.184$.

The Proof

Polytope: Convex hull of a set of points.

Convex hull: $\text{Conv}(\{v_1, \dots, v_n\})$ take $v_i \in \mathbb{R}^n$

$$\sum_{i=1}^n \lambda_i v_i \quad \text{st.} \quad \sum_{i=1}^n \lambda_i = 1 \quad \lambda_i \geq 0 \quad \forall i.$$

examples: polygons ... green cube.

~~Order Polytope.~~

Okay we said this had something to do w/ convex geometry ... why? Because we'll model

figuring out linear extensions as a polytope

II The order Polytope

Let's assign a convex polytope to partial orderings...

(Order Polytope): ~~Let (X, \leq) be an n -element poset~~ Let ~~coordinates in \mathbb{R}^n be indexed by~~ element

1. Take a poset (X, \leq) w/ n -elements

2. Index ~~vector in~~ \mathbb{R}^n by elements of X .
Coordinates in

3. The order polytope $P(\leq)$ is the set of all $x \in [0, 1]^n$ satisfying

$$x_a \leq x_b \quad \forall a, b \in X \text{ st. } a \leq b.$$

Equivalently this can be defined as...

1. Call $U \subseteq X$ an up set if

$$a \in U \text{ and } a \leq b \rightarrow b \in U.$$

that is if $a \in U$ then U contains all b larger than a according to \leq

2. The vertices of $P(\leq)$ are ~~the~~ exactly the characteristic vectors of all upsets in (X, \leq)

Example using defns...

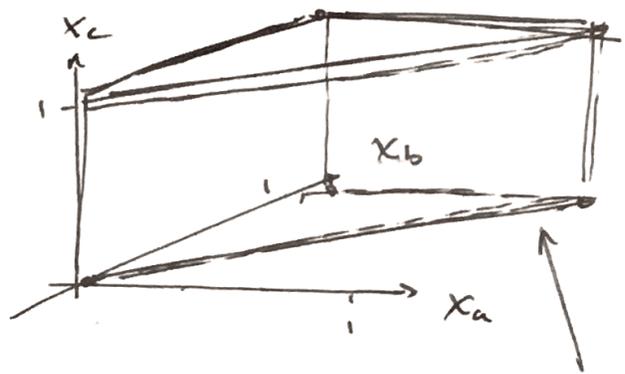
1. Take $\{a, b, c\}$ where $\preceq = \{(a, b)\}$. Then

$$x \in [0, 1]^n \text{ s.t.}$$

$$x_a \leq x_b.$$

Suppose $x \in \mathbb{R}^3$ is indexed as...

$$x = \begin{pmatrix} a \\ b \\ c \end{pmatrix}. \text{ Then.}$$



this region is $P(\preceq)$.

$$P(\preceq) = \{x \in [0, 1]^3 : x_a \leq x_b\}$$

2. Using the vertex defn.

- Vertices of $P(\preceq)$ = characteristic vectors of
all upsets

- Upset is $U \subseteq X$ s.t. if $a \in U$ and $b \succ a$
 $\rightarrow b \in U$.

- 3 cases to consider

• No ~~vertices~~ points in U

$\rightarrow \chi_u = \vec{0}$

} $\vec{0}$

• $a \in U$. Since $a \leq b$

$\rightarrow \{a, b\} \subseteq \chi_u$

} $\{a, b\} = \begin{pmatrix} 1 \\ 1 \\ 0 \end{pmatrix}$

} $\{a, b, c\} = \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix}$

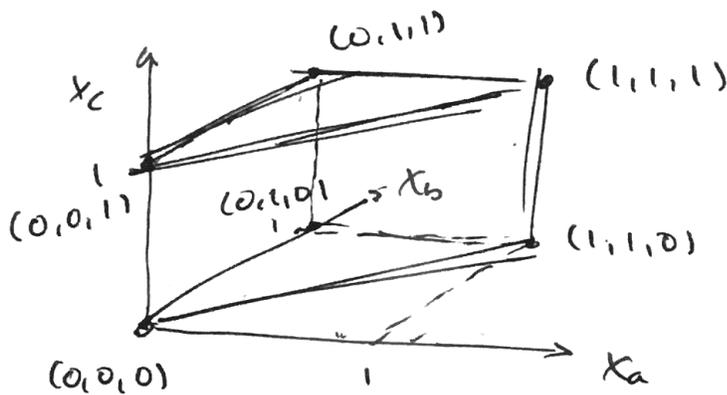
• $b \in U$. No requirements \rightarrow

$\{b\} = \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix}$

• $c \in U$. No requirements

$\{b, c\} = \begin{pmatrix} 0 \\ 1 \\ 1 \end{pmatrix}$

$\{c\} = \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix}$



Claim: Defn of $P(\leq)$ as set of pts. and as polytope whose vertices or upset characteristic vectors are equiv.

Proof: Observe...

1. Let U be an upset and χ_u its characteristic vector. Then claim $\chi_u \in P(\leq)$.

Consider any $(a, b) \in \leq$. There are two cases...

1. $a \in U$: Then by defn $b \in U$ since $a \leq b$.
this means

$$x_u(a) = x_u(b)$$

satisfying $x_u(a) \leq x_u(b) \rightarrow x \in P(\leq)$

2. $a \notin U$. Then $x_u(a) = 0 \leq x_u(b)$ since
 ~~$b \in \{0,1\}$~~ , $x_u(b) \in \{0,1\}$.

Next observe that these are the only integral vectors in $P(\leq)$.

- Any other integral vector must have

$$x_u(a) = 1 \geq x_u(b) = 0$$

but then since $a \leq b$, ~~$x_u(a) = 1$~~ $x \notin P(\leq)$

Finally observe that all vertices of $P(\leq)$ are integral

- Any vertex is the intersection of n , $(n-1)$ -dimensional hyperplanes.
- These hyperplanes must satisfy constraints like

$$x_a = 1 \quad \text{or} \quad x_a = 0 \quad \text{or} \quad x_a = x_b.$$

- Thus they can only intersect at integral pts. \square

Using this object we can say the following about partial and linear orders... (Before define simplex: Conv hull of a set of affine indpts...)

$\{v_1, \dots, v_n\}$ s.t. v_1, \dots, v_n lin ind.

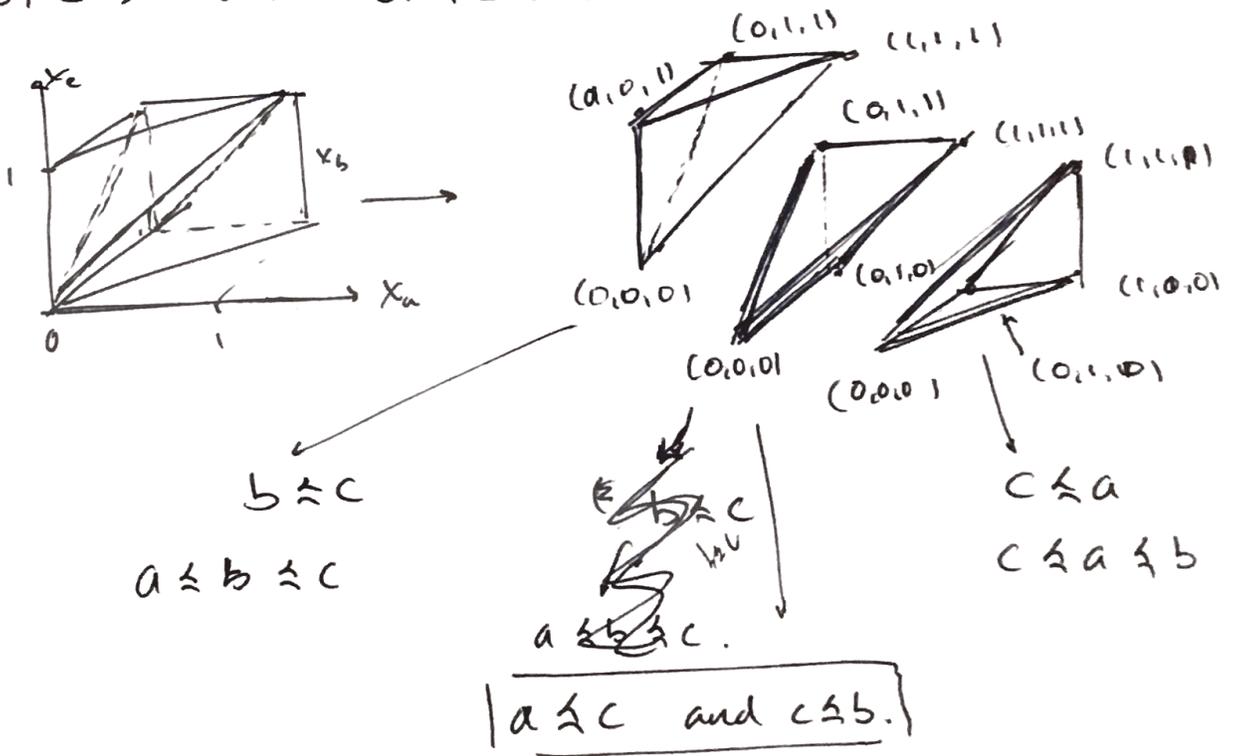
Claim: Let X be an n -element set... $\{v_1, \dots, v_n\}$ lin ind.

1. If \leq is a linear ordering on X then $P(\leq)$ has a volume of $\frac{1}{n!}$.
2. For any partial ordering \leq on X , the simplices of the form $P(\leq)$ where $\leq \in E(\leq)$ cover $P(\leq)$ and have disjoint interiors. Thus...

$$\text{Vol}(P(\leq)) = \frac{1}{n!} \cdot e(\leq).$$

To get a feel for ① observe...

1. $\{a, b, c\}$ w/ $a \leq b$...



Proof: We prove each claim... but a claim first.

(1): ~~WLOG assume $1 \leq \dots \leq n$. Then upset characteristic~~
~~vectors have the form~~

$$(\underbrace{0, \dots, 0}_i, 1, \dots, 1)$$

First: Observe $\mathcal{P}(\leq)$ is a simplex... WLOG assume
 $\leq := 1 \leq 2 \leq \dots \leq n$.

then upset characteristic vectors take the form...

$$x_u = (0 \dots 0, \underbrace{1, \dots, 1}_i) \rightarrow \text{there are } n \text{ of these.}$$

provided $i \in u$ is the smallest elem. Furthermore,
each x_u is affinely independent of one another

i.e. no way to write

$$\Leftrightarrow \sum \alpha_i x_{u(i)} = 0 \text{ w/ } \sum \alpha_i = 0$$

and $\alpha_i > 0$ for some i .

\Leftrightarrow Fix $x_{u(n)}$ then $\forall i \neq n$.

$$\{x_{u(i)} - x_{u(n)} : i \neq n\}$$

is linearly ind.

no need if
already
defined.

Assumes all
simplices are
congruent!

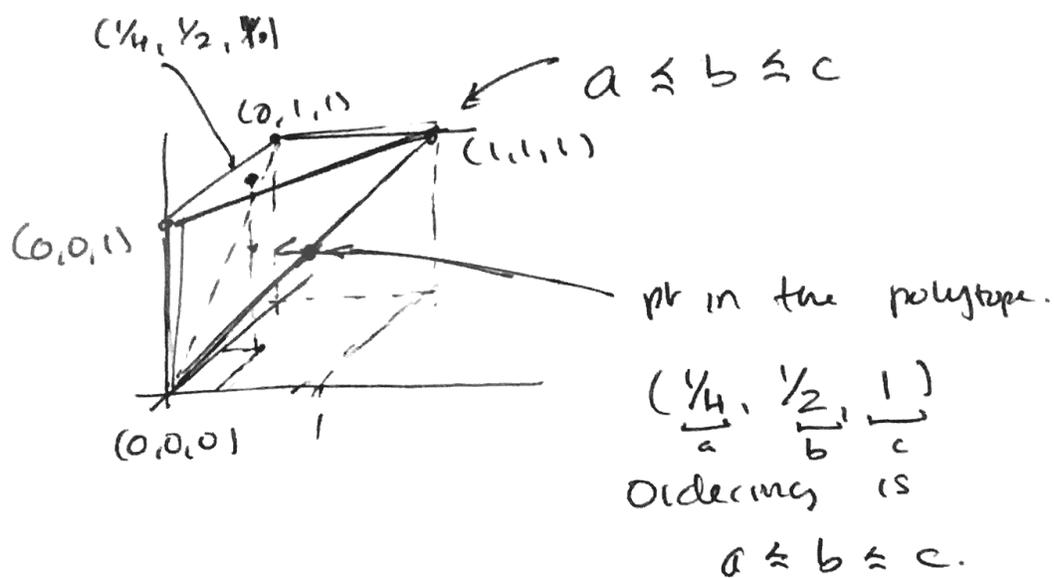
By defn. this is a simplex. \rightarrow you can always rearrange coordinates
to form this linear ordering

How to show our claims.

(2) : Observe that any point $(x_1, \dots, x_n) \in P(\leq)$

~~with~~ with distinct coordinates determines a unique linear order...

- the one determined by the natural ordering of its coordinates as real #s.



Furthermore $P(\leq) \subseteq P(\leq)$ by defn ~~the~~ $\forall \leq \in E(\leq)$

- Each point belongs to exactly one linear ordering simplex.

unless on boundary where a coord is =.

- $P(\leq) \subseteq P(\leq) \forall \leq \in E(\leq)$

\Rightarrow the simplices of $E(\leq)$ subdivide $P(\leq)$.

(1) : To see all linear order simplices have $\text{Vol} = \frac{1}{n!}$ ~~total~~

we want to utilize congruence and construct the space that has all total order simplices as subparts (via part 1 of (2)) then divide by # of possible ~~total~~ ^{linear} orders ($n!$)

— Take \leq to be the discrete ~~total~~ ^{partial} order
 $\leq = \{(1,1) \dots (n,n)\}$

— Its polytope is ^{bounded by} literally all $x \in \{0,1\}^n$
 \Rightarrow unit hypercube $\Rightarrow \text{Vol} = 1$

— $e(\leq) = \{\text{all possible orders}\} = n!$

— Volume of linear order simplex = $\frac{1}{n!}$

(2 pt 2) : To see $\text{Vol}(P(\leq))$ observe that each

$P(\leq)$ for $\leq \in E(\leq)$ has disjoint interiors by 2 pt 1. ^{each w/ vol = $\frac{1}{n!}$} thus

$$\text{Vol}(P(\leq)) = \frac{1}{n!} \cdot e(\leq). \quad \square$$

Height + Center of Gravity

Take X to be a finite set and \leq a linear order.
we define the height of a in \leq .

$$h_{\leq}(a) := \underbrace{|\{x \in X : x \leq a\}|}_{\# \text{ of elements smaller than } a.}$$

On a \preceq partial order...

$$\begin{aligned} h_{\preceq}(a) &:= \text{Avg}_{e \in E(\preceq)} \{h_{\leq}(a)\} \\ &= \frac{1}{e(\preceq)} \cdot \sum_{e \in E(\preceq)} h_{\leq}(a) \end{aligned}$$

Lemma 1: ~~For any distinct a, b~~ Given \leq , there exists distinct $a, b \in X$ s.t.

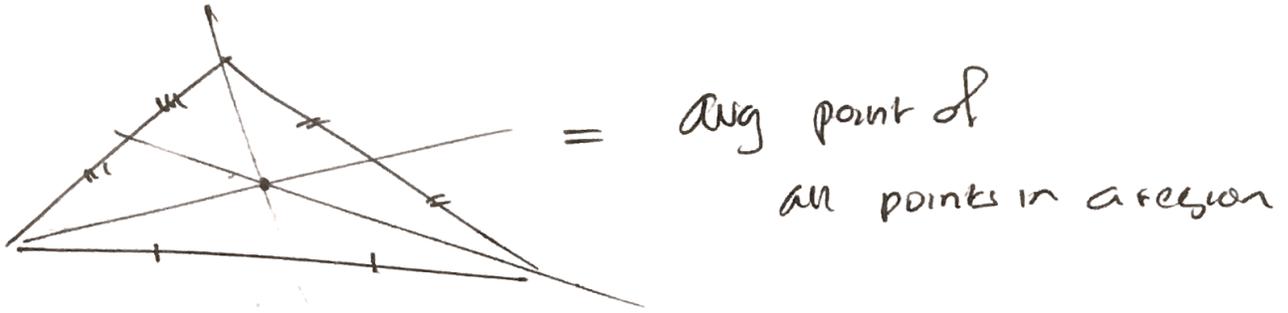
$$|h_{\leq}(a) - h_{\leq}(b)| < 1.$$

Lemma 2: For any n -element poset (X, \preceq) , the center of gravity of the order polytope $P(\preceq)$ is.

$$c = (\sum C_a : a \in X)$$

$$C_a = \frac{1}{n+1} h_{\preceq}(a).$$

What is the center of gravity? Probably recall it in Math 53.



Simplex: $\frac{1}{n+1} \sum_{i=1}^{n+1} x_i$ x_i vertices of simplex.

In general:

Proof of lemma: Since $P(\xi)$ for $\xi \in E(\xi)$ over $P(\xi)$, the center of gravity for $P(\xi)$ is the avg of centers of gravity for $P(\xi)$.

$$\text{Centroid}(P(\xi)) = \frac{1}{e(\xi)} \sum_{\xi \in E(\xi)} \text{Centroid}(P(\xi)).$$

To compute ~~the~~ centroid of $P(\xi)$ remember, we can always permute coordinates to ~~order~~ get the total order ~~1, 2, ..., n~~ $1 \leq 2 \leq \dots \leq n$.

the permutation for this has coordinates \swarrow vector

$$\left. \begin{array}{l} (0, \dots, 0) \\ (0, \dots, 1) \\ (0, \dots, 1, 1) \\ \dots \end{array} \right\} n \text{ times}$$

Observe ...

for a^{th} coord -

(0 ... 0, 0, 0)
(0 ... 0, 0, 1)
(0 ... 0, 1, 1)
(0 ... 1, 1, 1)

$n-a$ prs w/ a^{th} coord = 1.

$$\left[\text{Centroid} (P(\leq)) \right]_a = \underbrace{\frac{1}{n+1}}_{\# \text{ prs}} \cdot \underbrace{\sum_{i=a}^n 1}_{\substack{\# \text{ of } b \in X \text{ st. } b \geq a \\ = \text{height of } a}}$$

$$= \frac{1}{n+1} h_{\geq}(a)$$

$$\begin{aligned} \text{Thus ... } \left[\text{Centroid} (P(\leq)) \right]_c &= \frac{1}{e(\leq)} \sum_{\substack{b \in E(\leq) \\ b \geq a}} \frac{1}{n+1} \cdot h_{\geq} a \\ &= \frac{1}{n+1} h_{\leq}(a). \quad \square \end{aligned}$$